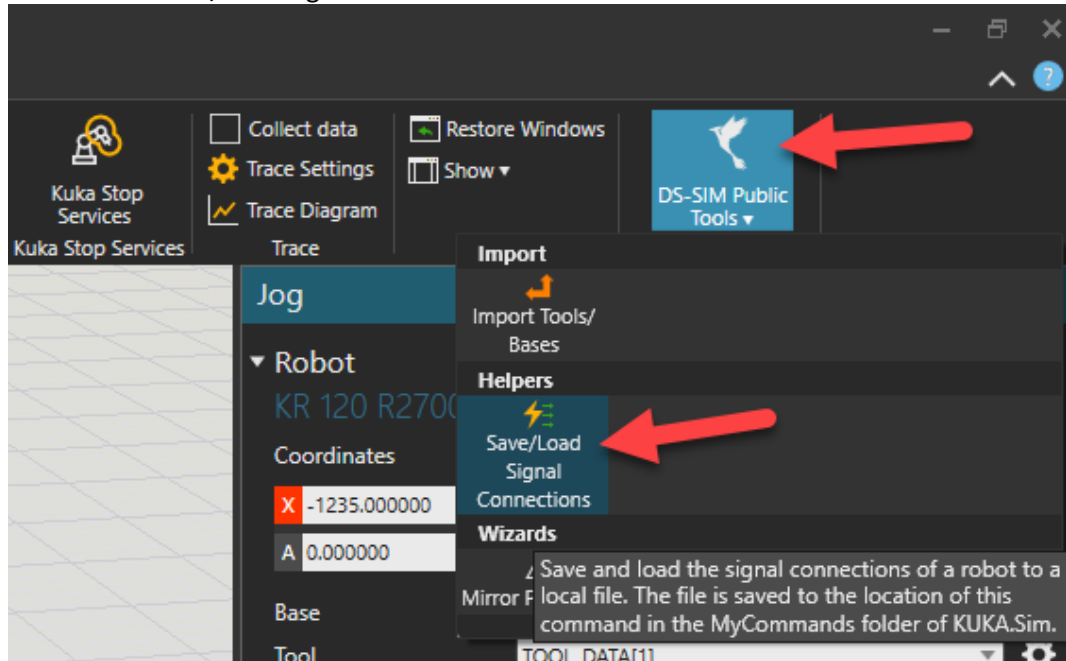


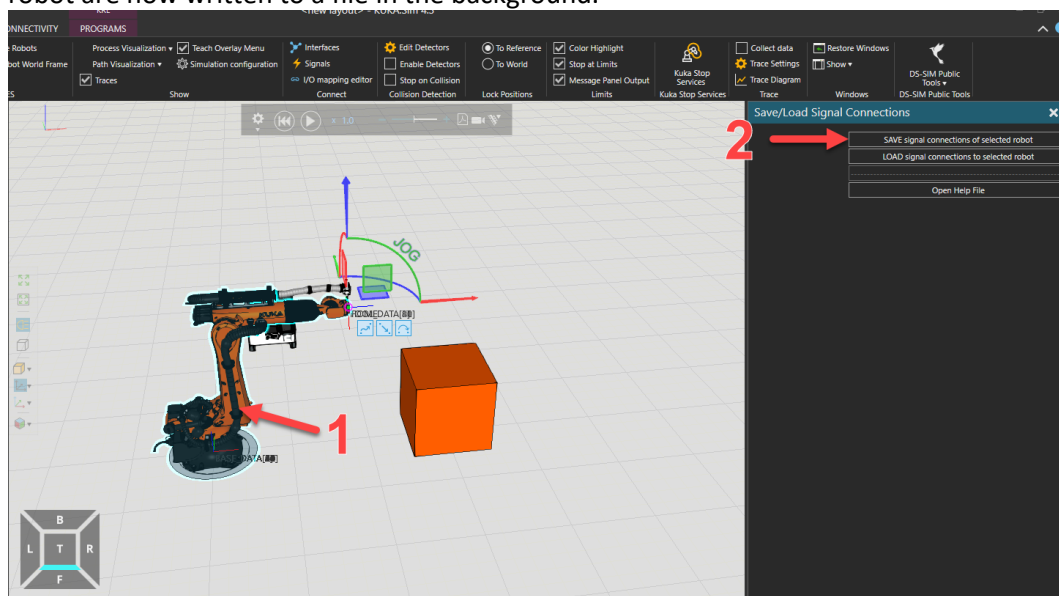
DS_SIM_Public_Tools

Save/Load Signal Connections

1. Execute the Save/Load Signal Connections command

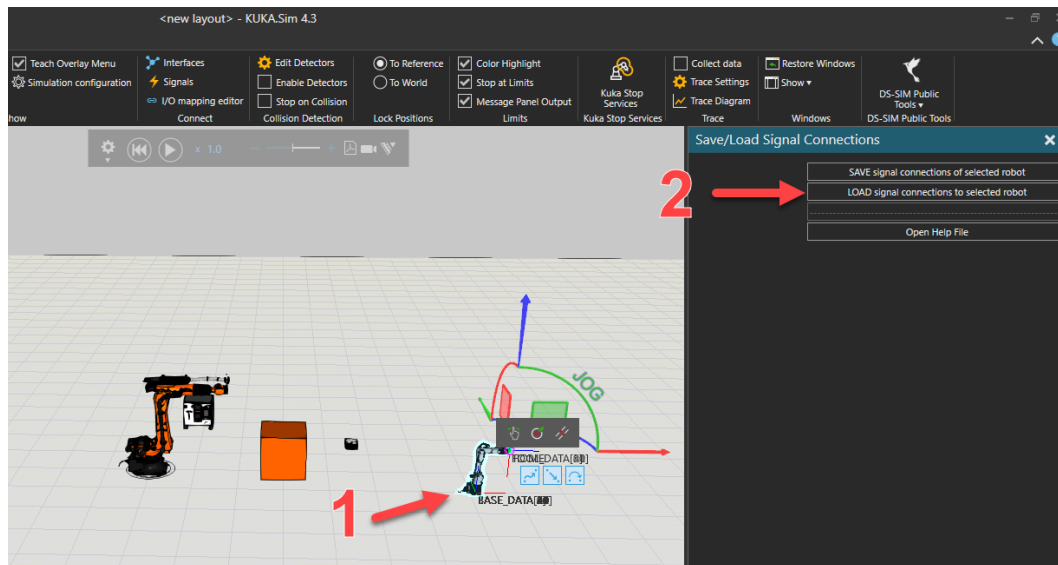


2. Select the robot and save all signal connections of this robot by clicking on the “Save signal connections of selected robot” button. All signal connections of the selected robot are now written to a file in the background.



DS_SIM_Public_Tools

3. Select another robot in the simulation scene or add a new robot from the eCat and select it. Then click on the “LOAD signal connections to selected robot” button to load all signal connections, that have been previously saved in the background file, to the selected robot.



4. Now the second robot shares the same signal connections as the first robot. This can be helpful for standard IO setups or if you need to manually exchange a robot in a simulation scene.

